

Two Functions & 2 Random Variables

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Given 2 RVs, X & Y , let $Z = g(X, Y)$, $W = h(X, Y)$

Where $\left. \begin{array}{l} g: \mathbb{R}^2 \rightarrow \mathbb{R} \\ h: \mathbb{R}^2 \rightarrow \mathbb{R} \end{array} \right\}$ what is the joint density function of Z & W ?
 $f_{ZW}(z, w)$?

* Use the change of variables approach (approach #2)

* If Z & W represent a linear transformation of X & Y

→ treat X & Y as a vector & Z & W are then the result of matrix multiplication

Example: Linear Transformation of a vector (X, Y)

$$\begin{bmatrix} Z \\ W \end{bmatrix} = A \begin{bmatrix} X \\ Y \end{bmatrix}, \text{ where } A \text{ is a } 2 \times 2 \text{ matrix}$$

$$\Rightarrow \left. \begin{array}{l} g(x, y) = a_{11}x + a_{12}y \\ h(x, y) = a_{21}x + a_{22}y \end{array} \right\} \& A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \leftarrow \begin{array}{l} \text{coefficient} \\ \text{matrix} \end{array}$$

AFFINE TRANSFORMATION

If A is a sine/cosine function of some angle θ , then this represents a rotation of the vector XY by the angle θ

could also be a projection

* Could find f_{ZW} by starting w/ CDF: $F_{ZW}(z, w) = P(Z \leq z, W \leq w)$
 $= P((X, Y) \in D_{ZW})$

Integrate the joint density f_{XY} of X & Y over the set D_{ZW} , to get the joint CDF of Z & W

where $D_{ZW} = \{(x, y) \in \mathbb{R}^2: \left. \begin{array}{l} g(x, y) \leq z, \\ h(x, y) \leq w \end{array} \right\}$
for every $z, w \in \mathbb{R}$

However, in practice it is too difficult \Rightarrow Instead, do change of variables approach (to find D_{ZW})

Change of Variables Approach (for 2 fn. & 2 RVs)

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* Assume $\begin{cases} z = g(x, y) \\ w = h(x, y) \end{cases}$ may be solved simultaneously in order to get:

$\begin{cases} x = g^{-1}(z, w) \\ y = h^{-1}(z, w) \end{cases}$ } Simultaneous Solution

(also assume that the partials of z, w w.r.t. x, y exists)

* Now $\begin{cases} g^{-1}: \mathbb{R}^2 \rightarrow \mathbb{R} \\ h^{-1}: \mathbb{R}^2 \rightarrow \mathbb{R} \end{cases}$ } for the case $\begin{bmatrix} z \\ w \end{bmatrix} = A \begin{bmatrix} x \\ y \end{bmatrix} \Rightarrow$ this means A^{-1} exists

* Result: It may then be shown that...

$$f_{z,w}(z, w) = \frac{f_{x,y}(g^{-1}(z, w), h^{-1}(z, w))}{\left| \frac{\partial(z, w)}{\partial(x, y)} \right|} \quad \leftarrow \text{(determinate)}$$

* Now find denominator term, where

$$\left| \frac{\partial(z, w)}{\partial(x, y)} \right| \equiv \left| \begin{bmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} \end{bmatrix} \right| \quad \leftarrow \text{(Abs. value of the determinate)}$$

$$= \begin{vmatrix} \frac{\partial z}{\partial x} & \frac{\partial z}{\partial y} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} \end{vmatrix}$$

$$\Leftrightarrow J \quad \left(\begin{array}{l} \text{"the Jacobian"} \\ \text{of the} \\ \text{transformation"} \end{array} \right)$$

Jacobian
Matrix

Jacobian Computation Example

* assuming the partials of Z & W w.r.t. X, Y exists & the determinant is not equal to zero

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X & Y be 2 ind. RVs that are independent and identically distributed (iid or i.i.d.) Gaussian RVs

where

$$\begin{cases} \mu_x = \mu_y = 0 \\ \sigma_x = \sigma_y = \sigma \\ r = 0 \end{cases}$$

let

$$\begin{cases} R = \sqrt{x^2 + y^2} \\ \Theta = \tan^{-1}(y/x) \end{cases} \quad \left. \begin{array}{l} \text{Polar} \\ \text{Coordinates} \end{array} \right\}$$

(theta)

... Change of Variables formula to get...

$$f_{R\Theta}(r, \theta) = \frac{r}{2\pi\sigma^2} \exp\left[-\frac{r^2}{2\sigma^2}\right] u(r), \quad -\pi \leq \theta \leq \pi$$

$$\Rightarrow f_R(r) = \int_{-\infty}^{\infty} f_{R\Theta}(r, \theta) d\theta$$

(which is just from $-\pi$ to π of the equation above)

$$= \frac{r}{\sigma^2} \exp\left[-\frac{r^2}{2\sigma^2}\right] u(r)$$

RAYLEIGH PDF

(Using CoV for finding 1 fn of 2 RVs)

* Note that for 1 fn of 2 RVs, sometimes it is easiest to find an auxiliary or dummy second function (via change of var.) in order to approach 2 functions of 2 RVs, then integrate to get the marginal pdf of interest

(Common choice is to let the 2nd rv be $W=X$ or $Z=Y$)

Joint Expectation

(Expectation may be viewed as the integration of a function times the density function)

Given 2 RVs, X & Y , let $Z = g(X, Y)$ for some $g: \mathbb{R}^2 \rightarrow \mathbb{R}$

then $E[Z] = \int_{-\infty}^{\infty} z f_z(z) dz$, however, instead of this

form, often used is the result that the expected value of $g(x, y)$ is ...

(“Linearity of expectation”)

$$E[Z] = E[g(X, Y)] = \iint_{\mathbb{R}^2} g(x, y) f_{XY}(x, y) dx dy$$

JE IS A LINEAR OPERATOR

CORRELATION

OR

$$E[Z] = \sum_{x \in \mathbb{R}_x} \sum_{y \in \mathbb{R}_y} g(x, y) P_{XY}(x, y)$$

Joint Expectation may take the form of a correlation b/w 2 RVs

(or correlation coefficient)

Commonly Used Forms (Still using $E[X], E[Y], \sigma_x^2, \sigma_y^2$)

$$|r_{xy}| \leq 1$$

$$\begin{aligned} \text{Corr}(X, Y) &\equiv E[XY] \\ \text{Cov}(X, Y) &\equiv E[(X - \mu_x)(Y - \mu_y)] \\ r_{xy} &\equiv \frac{\text{Cov}(X, Y)}{\sigma_x \sigma_y} \quad (\text{or } \rho_{xy}) \end{aligned}$$

← Correlation of X & Y
← Covariance of X & Y (normalized correlation)
← Correlation Coefficient
(via subtracting the means)

- * If X, Y are ind. $\Rightarrow r_{xy} = 0$ (converse is not necessarily true)
- * If $r_{xy} = 0 \Rightarrow X$ & Y are UNCORRELATED
- * If $E[XY] = 0 \Rightarrow X$ & Y are ORTHOGONAL

$\therefore X, Y$ are uncorrelated IFF
 $\text{Cov}(X, Y) = 0$
(or) $E[XY] = \mu_x \mu_y$ (show that either is true)

Cauchy-Schwarz inequality (useful for optimization)

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For RVs X & Y , the expected value of XY is less than or equal to sqroot of exp. val. of X^2 times exp. val. of Y^2

$$\Rightarrow |E[XY]| \leq \sqrt{E[X^2]E[Y^2]}$$

(abs value)

iff $Y = a_0 X$ with probability 1 for some constant $a_0 \in \mathbb{R}$

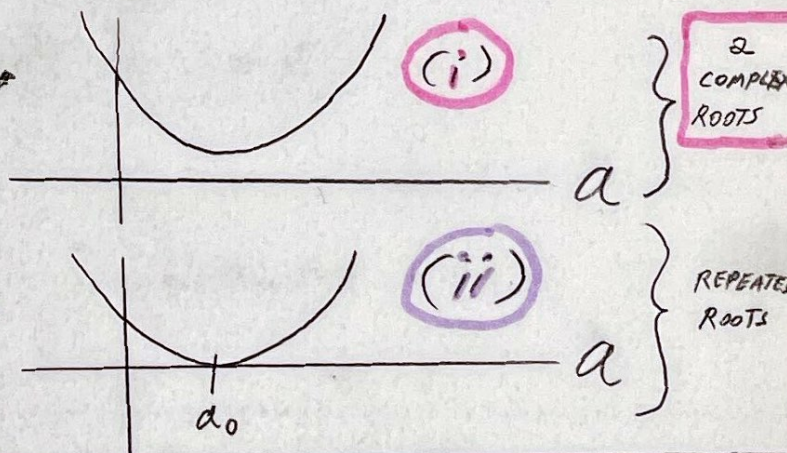
Consider the inequality: $0 \leq E[(aX - Y)^2] = a^2 E[X^2] - 2a E[XY] + E[Y^2]$

\Rightarrow (quadratic fr. of the real number a) $0 \leq E[(aX - Y)^2] = E[X^2]a^2 - 2E[XY]a + E[Y^2]$

$a \in \mathbb{R}$

2 Cases:

- (i) $E[(aX - Y)^2] > 0$
- (ii) $E[(aX - Y)^2] = 0$



(i) $4(E[XY])^2 - 4E[X^2]E[Y^2] < 0$

$$\Rightarrow E[XY] < \sqrt{E[X^2]E[Y^2]}$$

(ii) $\exists a_0 \in \mathbb{R} \mid E[(a_0 X - Y)^2] = 0$

\Rightarrow Can then be shown that if a RV X has $E[X^2] = 0$, then $X(\omega) = 0 \forall \omega \in \Omega$ except possibly on some set A with $P(A) = 0$ i.e. $\exists B \subset \Omega$ s.t. $X(\omega) = 0 \forall \omega \in B$

$Y = a_0 X$ with prob. 1

Characteristic & Moment Generating Functions

* Characteristic Function ← Alternative representation of the prob. distributions of a RV

(1 RV) Find char. fn of 1 RV X

$$\Phi_X(\omega) = E[e^{i\omega X}], \forall \omega \in \mathbb{R}$$

$$i = \sqrt{-1}$$

(Complex valued function)

$$\Phi_X(\omega) = \int_{-\infty}^{\infty} e^{i\omega x} f_X(x) dx, \forall \omega \in \mathbb{R}$$

(Fourier Transform - esque)

Measure P	
cdf	F
pdf	f
(pmp)	p
← (discrete RV, one for all RV)	
Char. fn	Φ
MGF	ϕ
← (for finding moments)	

- * finding moments
- * finding distributions for sums of RVs
- * modeling in some cases

(difference is the sign is negative in the exponential)

⇒ Can be shown that $f_X(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \Phi_X(\omega) e^{i\omega x} d\omega$

CF
MGF

* Moment Generating Function ← of RV X

$$\Phi_X(s) \equiv E[e^{sX}], s \in \mathbb{R} \text{ or } s \in \mathbb{C}$$

$$\Phi_X(s) = \int_{-\infty}^{\infty} e^{sx} f_X(x) dx$$

(Laplace Transform - esque)

* If density fn DNE, it is possible to define Φ_X & ϕ_X in terms of P or F_X

* It is possible for the char fn, Φ_X , to exist but the MGF, ϕ_X , DNE (e.g., Cauchy Random Variable function)

The Moment Generating Theorem

(expected value of $[X^n]$)

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Given RV X w/ mgf ϕ_X , the n^{th} moment of X may be computed as

$$E[X^n] = \phi^{(n)}(0) \equiv \left. \frac{d^n}{ds^n} \phi_X(s) \right|_{s=0}$$

("evaluated at zero") (n^{th} order derivative w.r.t. s)

$$\frac{d^n}{ds^n} \phi_X(s) = \frac{d^n}{ds^n} E[e^{sX}] = E\left[\frac{d^n}{ds^n} e^{sX}\right] = E[X^n e^{sX}]$$

$$\Rightarrow \phi^{(n)}(0) = E[X^n]$$

Similarly, the result may be written in terms of the characteristic function

(2 RV) The joint characteristic function of RVs X & Y :

$$\Phi_{XY}(\omega_1, \omega_2) \equiv E[e^{i(\omega_1 X + \omega_2 Y)}], \text{ for } \omega_1, \omega_2 \in \mathbb{R}$$

$$\Rightarrow \Phi_{XY}(\omega_1, \omega_2) = \iint_{\mathbb{R}^2} e^{i(\omega_1 x + \omega_2 y)} f_{XY}(x, y) dx dy = \sum \sum xy P_{XY}(x, y) \text{ for discrete RVs}$$

Joint MGF:

$$\Phi_{XY}(s_1, s_2) \equiv E[e^{s_1 X + s_2 Y}], s_1, s_2 \in \mathbb{C}$$

Joint Moments:

$$\mu_{j,k} = E[X^j Y^k] = \left. \frac{\partial^j \partial^k}{\partial s_1^j \partial s_2^k} \Phi_{XY}(s_1, s_2) \right|_{s_1=0, s_2=0}$$

* $\Phi_X(\omega) = \Phi_{XY}(\omega, 0), \forall \omega \in \mathbb{R}$ & $\Phi_Y(\omega) = \Phi_{XY}(0, \omega), \forall \omega \in \mathbb{R}$

* If $Z = aX + bY$ for $a, b \in \mathbb{R}$, then $\Phi_Z(\omega) = \Phi_{XY}(a\omega, b\omega)$

* If X, Y are ind. then $\Phi_{XY}(\omega_1, \omega_2) = \Phi_X(\omega_1) \Phi_Y(\omega_2)$

* If $Z = X + Y$ & X, Y are ind. then $\Phi_Z(\omega) = \Phi_X(\omega) \Phi_Y(\omega), \forall \omega \in \mathbb{R}$

* If $Z = X + Y$ & X, Y are i.i.d.
 $\Phi_Z(\omega) = (\Phi_X(\omega))^2$

\therefore density fn of $Z \Leftrightarrow$ convolution of density fn of X & density fn of Y

Conditional Distributions for 2 RVs

* Recall: Conditional CDF of RV X , given that event B occurs, is

$$F_X(x|B) \equiv P(X \leq x | B), \text{ if } P(B) > 0$$

* Consider: $B = \{y_1 < Y \leq y_2\}$, for RV Y & $y_1, y_2 \in \mathbb{R}$, $y_1 < y_2$

* Derive: $f_X(x|Y=y)$, for $y \in \mathbb{R}$

$$\begin{aligned} \text{(Conditional Probability)} &\Rightarrow F_X(x | y_1 < Y \leq y_2) = \frac{P(X \leq x, y_1 < Y \leq y_2)}{P(y_1 < Y \leq y_2)} = \frac{F_{XY}(x, y_2) - F_{XY}(x, y_1)}{F_Y(y_2) - F_Y(y_1)} \\ &\quad \uparrow \text{(Conditional CDF)} \qquad \qquad \qquad \uparrow \text{(differentiate w.r.t. " " to get cond. PDF)} \end{aligned}$$

* Integral Form:

$$f_X(x | y_1 < Y \leq y_2) = \frac{\partial}{\partial x} \left[\int_{-\infty}^x \int_{-\infty}^{y_2} f_{XY}(x', y) dx' dy - \int_{-\infty}^x \int_{-\infty}^{y_1} f_{XY}(x', y) dx' dy \right]$$

$$= \frac{\int_{-\infty}^{y_2} f_{XY}(x, y) dy - \int_{-\infty}^{y_1} f_{XY}(x, y) dy}{F_Y(y_2) - F_Y(y_1)} = \int_{y_1}^{y_2} f_{XY}(x, y) dy$$

* Want to condition on $\{Y=y\}$, $y \in \mathbb{R}$?

⇒ Define:

$$f_X(x|Y=y) \equiv \lim_{\Delta y \rightarrow 0} \left[f_X(x | y < Y \leq y + \Delta y) \right]$$

* Let $y_1 = y$, $y_2 = y + \Delta y$

$$\Rightarrow f_X(x | y < Y \leq y + \Delta y) = \frac{\int_y^{y+\Delta y} f_{XY}(x, y') dy'}{F_Y(y+\Delta y) - F_Y(y)}$$

* Multiply by $\frac{(1/\Delta y)}{(1/\Delta y)}$ & then take the limit of the numerator & denominator as $\Delta y \rightarrow 0$

$$\Rightarrow f_X(x|Y=y) = \frac{f_{XY}(x, y)}{f_Y(y)}$$

* Notation: $f_{XY}(x|y) \equiv f_X(x|Y=y)$, often written as $f(x|y)$ in practice

$$f_{X|Y}(x|y) = \frac{f_{XY}(x, y)}{f_Y(y)} \quad \&\& \quad f_{Y|X}(y|x) = \frac{f_{XY}(x, y)}{f_X(x)}$$

⇒ Bayes' Theorem:

$$f_{X|Y}(x|y) = \frac{f_{Y|X}(y|x) f_X(x)}{f_Y(y)}, \quad \forall (x, y) \in \mathbb{R}$$

Total Probability Law:

$$f_Y(y) = \int_{-\infty}^{\infty} f_{XY}(x, y) dx = \int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx$$

3 Forms of Bayes' Theorem (Summary)

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* Note for X & Y as ind. RVs,

$$f_{Y|X}(y|x) = \frac{f_{XY}(x,y)}{f_X(x)} = \frac{f_X(x) f_Y(y)}{f_X(x)} = f_Y(y)$$

} (i.e., $f_{Y|X}(y|x)$ does not depend on x)

① $P(A|B) = \frac{P(B|A)P(A)}{P(B)}$, $A, B \in \mathcal{F}$ (for when X & Y are DISCRETE)

where $A = \{X=x\}$, $B = \{Y=y\} \Rightarrow P_{Y|X}(y|x) = \frac{P_{X|Y}(x|y)P_Y(y)}{P_X(x)}$

where $P_{Y|X}(y|x) \equiv P(Y=y|X=x)$ & $P_{X|Y}(x|y) \equiv P(X=x|Y=y)$

(Conditional pmfs)

$$\forall x \in \mathcal{R}_X, y \in \mathcal{R}_Y$$

② $P(A|Y=y) = \frac{f_Y(y|A)P(A)}{f_Y(y)}$, $A \in \mathcal{F}$ (for when Y is CONTINUOUS, X is DISCRETE)

where $A = \{X=x\}$, $x \in \mathcal{R}_X \Rightarrow P_{X|Y}(x|y) = \frac{f_{Y|X}(y|x)P_X(x)}{f_Y(y)}$

③ $f_{Y|X}(y|x) = \frac{f_{X|Y}(x|y)f_Y(y)}{f_X(x)}$ (for when X & Y are CONTINUOUS)

Conditional Expectation (3rd form of expectation)

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* Recall: Expectation is the integral of a function g times the density function

* In this case, the density function is a conditional density function

* Let X, Y be 2 RVs on $(\mathcal{S}, \mathcal{F}, P)$, & $g: \mathbb{R}^2 \rightarrow \mathbb{R}$

\Rightarrow What is the expected value of $g(X, Y)$ given that $Y = y$

$$E[g(X, Y) | Y = y] = \iint_{\mathbb{R}^2} g(x, y') f_{XY}(x, y' | Y = y) dx dy'$$

(Conditioning on a continuous RV equaling a particular real value with the event probability 0)

\Rightarrow Conditioning on $y < Y \leq y + \Delta y$ & letting $\Delta y \rightarrow 0$

* Can then show that:

$$E[g(X, Y) | Y = y] = \int_{-\infty}^{\infty} g(x, y) f_{XY}(x | y) dx$$

Note that it can be shown:

$$E[g(X, Y) | Y = y] =$$

$$E[g(X, y) | Y = y]$$

(Now X is the only random variable)

* Often have $g(X, Y) = g(X)$

$$\Rightarrow E[g(X) | Y = y] = \int_{-\infty}^{\infty} g(x) f_{X|Y}(x | y) dx \leftarrow \text{Special case}$$

* Another special case: $g(X) = X$

$$\Rightarrow E[X | Y = y] = \int_{-\infty}^{\infty} x f_{X|Y}(x | y) dx \leftarrow \text{Used in iterated expectation}$$

Conditional Expectation: Iterated Expectation

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* Sometimes it is easiest to find $E[g(X,Y)]$ via $f_{Y|X}(y|x)$ & $f_X(x)$ instead of the joint density $f_{XY}(x,y)$

$$\Rightarrow E[g(X,Y)] = \iint_{\mathbb{R}^2} g(x,y) f_{XY}(x,y) dx dy = \int_{\mathbb{R}^2} f_X(x) g(x,y) f_{Y|X}(y|x) dy dx$$

(joint density function) (conditional density \times marginal density)

$$E[g(X,Y)] = \int_{\mathbb{R}} f_X(x) \underbrace{E[g(X,Y)|X=x]}_{h(x)} dx$$

* Note that $E[g(X,Y)|X=x]$ is a function of $x \in \mathbb{R}$, this function is called h

$$\Rightarrow h(x) \equiv E[g(X,Y)|X=x] \quad h: \mathbb{R} \rightarrow \mathbb{R} \quad \left(\text{thus, we can create a RV } h(X) \text{ via making it depend on } X \right)$$

$$\therefore h(X) \equiv E[g(X,Y)|X] \quad (\text{DIFFERENT FUNCTIONS})$$

$$\Rightarrow E[g(X,Y)] = \int_{\mathbb{R}} E[g(X,Y)|X=x] f_X(x) dx = \int_{\mathbb{R}} h(x) f_X(x) dx = E[h(X)]$$

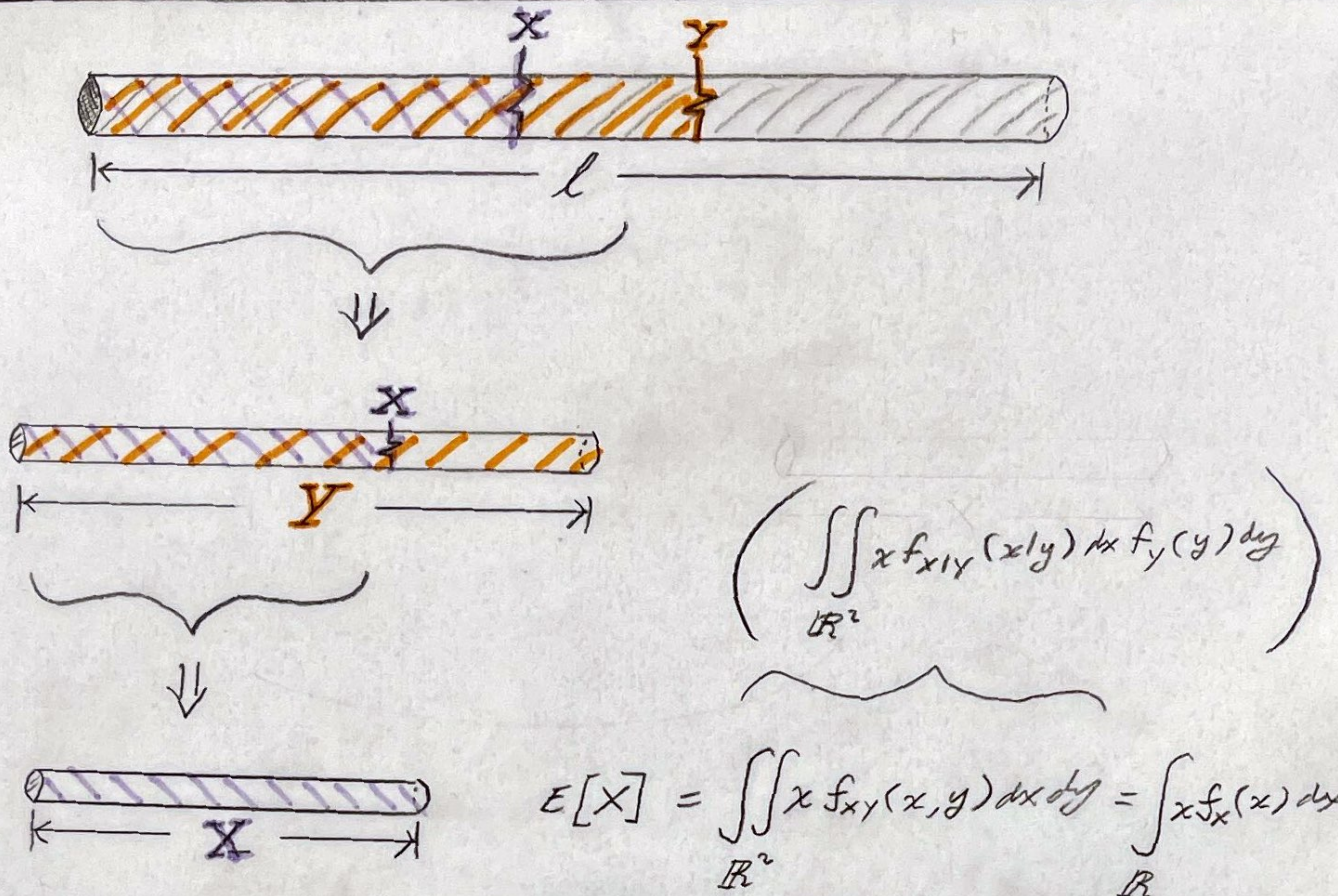
* Alternative Notation: $E[g(X,Y)] = E[E[g(X,Y)|X]]$

"Iterated Expectation"

* Important case: $g(X,Y) = Y \Rightarrow E[Y] = E[E[Y|X]]$

Iterated Expectation Example

* let l be the length of a stick, & then suppose breaking the stick at a uniformly chosen point Y , & then again at a uniformly chosen point X . Find $E[X]$



* Do not know f_{XY} or f_X
 * Do know $f_{X|Y}$ and f_Y

$f_Y(y) = 1/l, 0 \leq y \leq l$
 $f_{X|Y}(x|y) = 1/y, 0 \leq x \leq y$

now use $E[X] = E[E[X|Y]]$

$$\Rightarrow E[X|Y] \leftarrow \text{Find from } E[X|Y=y] = \int_{x=0}^{x=y} x f_{X|Y}(x|y) dx = \int_{x=0}^{x=y} x \left(\frac{1}{y}\right) dx = \frac{x^2}{2y} \Big|_{x=0}^{x=y}$$

$$\Rightarrow E[X|Y=y] = \frac{y}{2} \equiv h(y) \quad \therefore h(y) = \frac{y}{2}$$

$$\Rightarrow E[X|Y] = h(Y) = \frac{Y}{2}$$

$$\therefore E[X] = E[E[X|Y]] = E\left[\frac{Y}{2}\right] = \frac{1}{2} E[Y] = \frac{l}{4}$$

$\therefore Y$ is a uniform RV on $[0, l]$

Since X is uniform on $[0, y]$ given $Y=y$