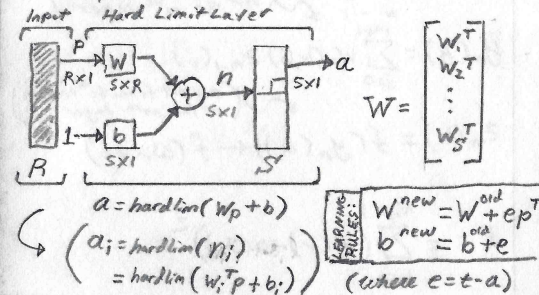


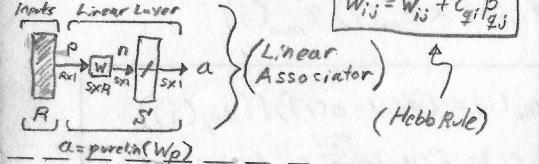
# Perceptron:



**Decision Boundary:**  $W_i^T p + b_i = 0$

- \* Always orthogonal to weight vector
- \* Single-layer perceptron can only classify linearly separable vectors

# Supervised Hebbian Learning:



$W = t_1 p_1^T + t_2 p_2^T + \dots + t_q p_q^T$   
 $\Rightarrow W = [t_1 t_2 \dots t_q] \begin{bmatrix} p_1^T \\ p_2^T \\ \vdots \\ p_q^T \end{bmatrix} \equiv TP^T$

# Pseudo-inverse Rule: $W = TP^+$

\* If  $R$  (# of rows)  $>$   $Q$  (# of columns) & all columns of  $P$  are independent  
 $\Rightarrow P^+ = (P^T P)^{-1} P^T$

# Hebbian Learning Variations:

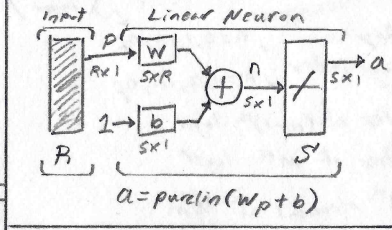
- \* Filtered Learning  $\Rightarrow W^{\text{new}} = (1+r)W^{\text{old}} + \alpha t_q p_q^T$
- \* Delta Rule  $\Rightarrow W^{\text{new}} = W^{\text{old}} + \alpha (t_q - a_q) p_q^T$
- \* Unsupervised Hebb  $\Rightarrow W = W^{\text{old}} + \alpha a_q p_q^T$

# Pattern Classification: (bias = -1)

\* Use Symmetrical Hard Lim:  $\begin{cases} a = -1, n < 0 \\ a = +1, n \geq 0 \end{cases}$  (any plot)

\* Not linearly separable if classes on 2D plane cannot be separated by linear decision boundary

# ADALINE:



**Mean Square Error (MSE):** if no bias  $\Rightarrow W^{\text{new}} = W^{\text{old}} + \alpha p e^T$   
 $b^{\text{new}} = b^{\text{old}} + \alpha e$  (where  $e = t - a$ )

$F(x) = E[e^2] = E[(t - a)^2]$   
 $\Rightarrow F(x) = E[(t - x^T z)^2]$  where  $\begin{cases} x = [w \\ b] \\ z = [p \\ 1] \end{cases}$   
 $\Rightarrow F(x) = c - 2x^T h + x^T R x$   
 $(c = E[t^2], h = E[tz], R = E[zz^T])$

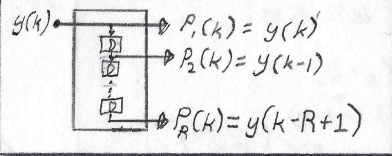
\* If a unique minimum exists, it is  $x^* = R^{-1}h$  (Hessian = 2R)

# LMS Algorithm:

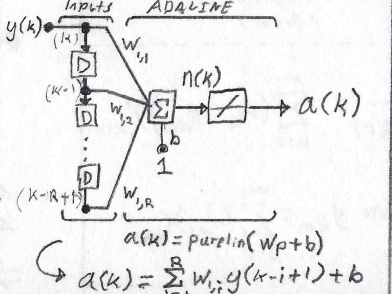
$W(k+1) = W(k) + 2\alpha e(k) p^T(k)$   
 $b(k+1) = b(k) + 2\alpha e(k)$

\* Convergence point  $\Rightarrow x^* = R^{-1}h$   
 \* Stable Learning Rate  $\Rightarrow 0 < \alpha < 1 / \lambda_{\text{max}}$  (where  $\lambda_{\text{max}}$  is maximum eigenvalue of  $R$  (find det))

# Tapped Delay Line:

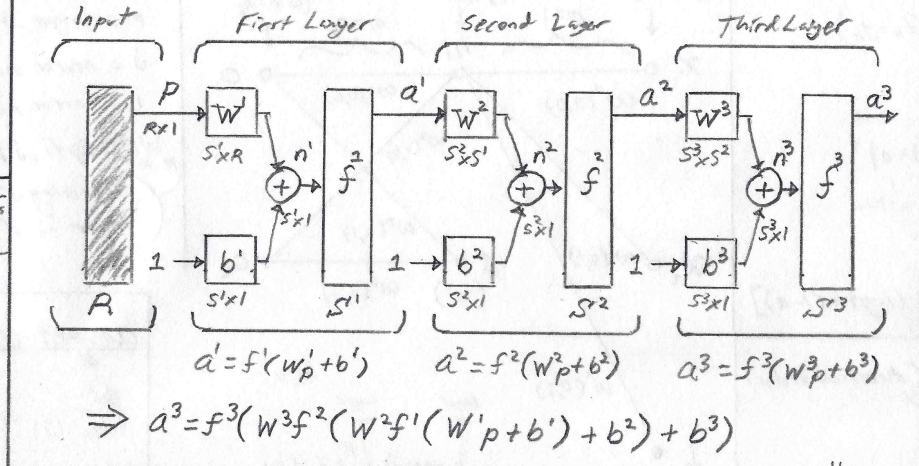


# Adaptive Filter ADALINE:



# Multilayer Network:

(if classification problem,  $P, P_2$  are coordinate inputs, 1st layer represents linear decision boundaries, 2nd layer "groups" them into regions, 3rd classifier)



# Backpropagation:

\* Performance Index  $\Rightarrow F(x) = E[e^T e] = E[(t - a)^T (t - a)]$   
 \* Approximate Performance Index  $\Rightarrow F(x) = e^T(k) e(k) = (t(k) - a(k))^T (t(k) - a(k))$   
 \* Sensitivity  $\Rightarrow S^m \equiv \frac{\partial F}{\partial n^m} = \begin{bmatrix} \frac{\partial F}{\partial n_1^m} \\ \frac{\partial F}{\partial n_2^m} \\ \vdots \\ \frac{\partial F}{\partial n_{S^m}^m} \end{bmatrix}$

# Feed Propagation:

$a^0 = p$  ← first layer neurons  
 $a^{m+1} = f^{m+1}(W^{m+1} a^m + b^{m+1})$ , for  $m = 0, 1, \dots, M-1$   
 $a = a^M$  ← last layer outputs

**Bwd Propagation:**  
 $S^M = -2 \dot{f}^M(n^M) (t - a)$   
 $S^m = \dot{f}^m(n^m) (W^{m+1})^T S^{m+1}$ , for  $m = M-1, \dots, 2, 1$

# Weight Update (Approximate Steepest Descent)

$W^m(k+1) = W^m(k) - \alpha S^m (a^{m-1})^T$   
 $b^m(k+1) = b^m(k) - \alpha S^m$

for output  $j$ : if  $t(k) = \frac{\partial}{\partial g(x)} y(k)$   
 connection  $\frac{\partial F}{\partial w_{ij}^m} = (t(k) - a(k)) \dot{f}^m(x) w_{ij}^m$   
 $\Delta w_{ij}^m = -\alpha (t(k) - a(k)) \dot{f}^m(x) w_{ij}^m$   
 $\Delta b_j^m = -\alpha (t(k) - a(k)) \dot{f}^m(x)$  for  $k = 1, \dots, K-1$

Hard Limit  $a = 0, n < 0$   
 $a = 1, n \geq 0$

Linear (purlin)  $a = n$   
 $f(x) = x, f'(x) = 1$

Log-Sig  $f = \frac{1}{1 + \exp(-x)}$   
 $f' = f(x)(1 - f(x))$

Hyp. Tangent (tansig)  $f = \frac{e^x - e^{-x}}{e^x + e^{-x}}, f' = 1 - f(x)^2$

Bipolar Sigmoid ( $\tanh(\frac{x}{2})$ )  
 $f = \frac{2}{1 + e^{-x}} - 1 = \frac{1 - e^{-x}}{1 + e^{-x}}$   
 $f' = \frac{1}{2} (1 + f)(1 - f)$

Network tries to fit params. to target  $d$   
 $[W] \begin{bmatrix} x \\ 1 \end{bmatrix} = [d] \begin{bmatrix} w \\ b \end{bmatrix} = d$

$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ , find det (2x2)  
 $\Rightarrow \det(A - \lambda I)$   
 $\Rightarrow \det(A - \lambda I) = 0$  & solve  
 $\det(A - \lambda I) = 0$   
 $(a - \lambda)(d - \lambda) - bc = 0$

Derivative Rules:  
 $\frac{d}{dx} f(g(x)) = f'(g(x)) g'(x)$   
 $\frac{d}{dx} f(x)g(x) = f'g + fg'$   
 $\frac{d}{dx} \frac{f(x)}{g(x)} = \frac{f'g - fg'}{g^2}$

Exponent Rules:  $\ln(x^a) = a \ln(x)$   
 $b^n \cdot b^m = b^{n+m}$   
 $(b^n)^m = b^{n \cdot m}$

$E(W) = E(w_1, w_2)$   
 $\nabla E(W) = \left\langle \frac{\partial E}{\partial w_1}, \frac{\partial E}{\partial w_2} \right\rangle$

**Cost Functions:**

MSE:  $E_m = \frac{1}{2} \sum_{k=1}^M (t_k - y_k)^2$

Quadratic:  $C(w, b) = \frac{1}{2n} \sum_x |y(x) - o|^2$   
desired actual

Cross-Entropy:  $C = -\frac{1}{n} \sum_x [y \ln(a) + (1-y) \ln(1-a)]$

GD:  $w_{k+1} = w_k + \lambda_k D_k$   
(direction vector)

CG:  $D_k = -G(w_k)$ , for  $k=1$   
 $D_k = -G(w_k) + b_k D_{k-1}$ , for  $k > 1$   
 $b_k = \frac{G(w_k) - G(w_{k-1})}{|G(w_{k-1})|^2}$   
 $\lambda_k = \frac{|G(w_k)|^2}{D_k^T A D_k}$

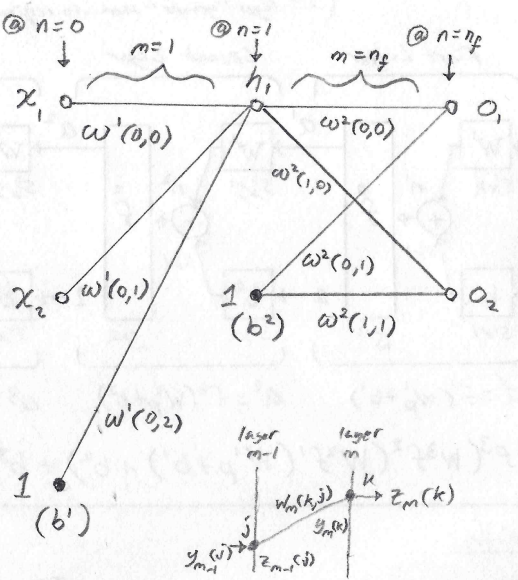
Softmax Activation: (similar to probability)  
 $a_j = \frac{e^{z_j}}{\sum_k e^{z_k}}$  &  $\sum_j a_j = 1$

Fast Computations: (Matlab)  
 $D_{ij} = \sum (x_i - y_j)^2$   
 $\Rightarrow D = b5 \times \text{fun}(@\text{plus}, \text{data}(k, x_i), \text{dot}(y, y), 1) - 2(x' \cdot y)$

def vector(): (Python)  
 $x = \text{numpy.arange}(a, b, \text{delta})$   
 return (f(x) \* delta), sum(c)

np.where (condition, true, false)  
 return when c is true

**3-2-2 Backpropagation Network**



$n = \text{layer index}, n = 0, 1, \dots, n_f$   
 $m = \text{weight stage index}, m = 1, 2, \dots, n_f$   
 $j = \text{neuron index of } (m-1)^{\text{th}} \text{ layer}$   
 $i = \text{neuron index of } m^{\text{th}} \text{ layer}$   
 $W_m(i, j) \Rightarrow (i, j)^{\text{th}} \text{ element of } W_m$   
 (connecting  $j^{\text{th}}$  node from  $(m-1)^{\text{th}}$  layer to  $i^{\text{th}}$  node of layer  $m$ )

$y_m(k) = \sum_{j=0}^{n_{m-1}} W_m(k, j) z_{m-1}(j)$   
(input to  $k^{\text{th}}$  neuron at the  $m^{\text{th}}$  layer)  
 $z_m(k) = f(y_m(k)) + f(ax+b)$   
(output from  $k^{\text{th}}$  neuron at the  $m^{\text{th}}$  layer)  
 $E = \frac{1}{2} \sum_{k=0}^{n_{np}-1} (d(k) - o(k))^2$

Weight updates  $\Rightarrow \Delta W_m(i, j) = -\alpha \frac{\partial E}{\partial W_m(i, j)}$   
(\*Note that  $S_m^*$  is not needed if it does not connect to prior layers)

$\frac{\partial E}{\partial W_m(i, j)} = \frac{\partial E}{\partial y_m(i)} \frac{\partial y_m(i)}{\partial W_m(i, j)}$   
 $\frac{\partial y_m(i)}{\partial W_m(i, j)} = z_{m-1}(j)$   
 $\Rightarrow \Delta W_m(i, j) = \alpha S_m(i) z_{m-1}(j)$   
 \* let  $-S_m(i) = \frac{\partial E}{\partial y_m(i)}$

$S_{n_f}(i) = (d(i) - o(i)) f'(y_{n_f}(i))$   
 $S_m(i) = f'(y_m(i)) \sum_{k=0}^{n_{m+1}-1} S_{m+1}(k) W_{m+1}(k, i)$

- i) Output Layer ( $m = n_f$ )  
 $-S_m(i) = -S_{n_f}(i) = \frac{\partial E}{\partial y_{n_f}(i)} = \frac{\partial E}{\partial o(i)} \frac{\partial o(i)}{\partial y_{n_f}(i)} = -(d(i) - o(i)) f'(y_{n_f}(i))$
- ii) Hidden Layer ( $m = 1$ )  
 $S_m(i) = \frac{\partial E}{\partial y_m(i)} = \frac{\partial E}{\partial z_m(i)} \frac{\partial z_m(i)}{\partial y_m(i)} = \frac{\partial E}{\partial z_m(i)} f'(y_m(i))$   
 $= \sum_{k=0}^{n_{m+1}-1} \frac{\partial E}{\partial y_{m+1}(k)} \frac{\partial y_{m+1}(k)}{\partial z_m(i)} = \sum_{k=0}^{n_{m+1}-1} \frac{\partial E}{\partial y_{m+1}(k)} W_{m+1}(k, i)$

BP (Non linear delta rule):  
 Fast input:  $x(n-1) = [x(n-1) \dots x(n-1)]^T$   
 Targets:  $w = [w_1, w_2, \dots, w_m]^T$   
 Prediction Order:  $M$  (data points)  
 Future Prediction:  $\hat{x}(n | x_{n-1})$   
 $w(n+1) = w(n) + \alpha e(n) x(n)$ , incl.  $M$

$g_m(i, j) = -S_m(i) z_{m-1}(j)$   
 $z_{m-1}(j) = \text{output of node } j \text{ in layer } (m-1)$   
 $S_{n_f}(i) = (d(i) - o(i)) f'(y(i))$   
 $S_m(i) = f'(y_m(i)) \sum_{k=0}^{n_{m+1}-1} S_{m+1}(k) W_{m+1}(k, i)$ , for  $m < n_f$

$\Rightarrow$  BP w/ Momentum: (@ iteration  $k=1$ , first Epoch, new term is zero)  
 $\Delta W_m^{k+1}(i, j) = \alpha S_m(i) z_{m-1}(j) + \beta \Delta W_m^k(i, j)$   
(momentum term)

Linear Delta Rule:  
 $w x_k = D_k$   
 $E(w) = \sum_{k=0}^{m-1} |d_k - w x_k|^2$   
(Error)

$\frac{\partial E}{\partial w(m, n)} = -\sum_{k=0}^{m-1} (d_k - y_k) x_{kn}$   
(where  $y_{km} = \sum_{j=0}^{n-1} w_{mj} x_{kj}$ )

Ex:  $y(t) = w^0(t) x(t) + b(t)$   
 $y_o(t) = f(w(t) x(t) + b(t))$   
(output after activation)  
 $E(w) = \frac{1}{2} (d(t) - y_o(t))^2$   
(desired) (actual)  
 $G(w) = \nabla E = -(d(t) - y_o(t)) f'(y(t)) x(t)$   
 $\Delta w(t) = -\alpha G(w) = \alpha z(t) x(t)$   
 $\Delta b(t) = -\alpha z(t)$   
 $\Rightarrow \Delta w(t) = \alpha (d(t) - y_o(t)) x^t(t)$   
(for  $f(\cdot) =$  identity fn (LMS))